

## A NOTE ON $\Omega$ -CONNECTEDNESS

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**Abstract.** Connectedness plays an important part in the study of topology. Several authors have generalized this notion by using generalized open and closed sets. In [9], the concept of  $\Omega$ -open and  $\Omega$ -closed sets have been introduced and studied. By using these set, we have introduced  $\Omega$ -connectedness and investigated its properties.

### 1 Introduction

Let  $X$  be a topological space. In 1982, Hdeib [10] introduced the notion of  $\omega$ -closeness. Using this concept, he introduced and studied  $\omega$ -continuity. In 1968, the notions of  $\theta$ -open subsets,  $\theta$ -closed subsets and  $\theta$ -closure were introduced by Veličko [20] for the purpose of studying the important class of  $H$ -closed spaces in terms of filter bases. He also showed that the collection of  $\theta$ -open sets in a topological space  $X$  itself forms a topology  $\mathfrak{S}_\theta$  on  $X$ . Dickman and Porter [4], [5], Joseph [13] extended the work of Veličko to study further properties of  $H$ -closed spaces. Noiri and Jafari [17], Caldas et al. [1] and [2], Steiner [18] and Cao et al [3] have also obtained several new and interesting results related to these sets. In [9], we have introduced the concept of  $\Omega$ -open,  $\Omega$ -closed sets and studied their properties. Exploiting this concept, in this paper, we introduce and study the notion of  $\Omega$ -connectedness. We start with the idea of  $\Omega$ -separated sets which is keynote in introducing  $\Omega$ -connectedness.

### 2 Preliminaries

Throughout this paper a space will always mean a topological space on which no separation axioms are assumed unless otherwise explicitly stated. Let  $(X, \mathfrak{S})$  be a space and let  $A$  be a subset of  $X$ . The closure and interior of  $A$  are denoted as  $\text{cl}(A)$  and  $\text{int}(A)$  respectively. A point  $x \in X$  is called a clocondensation point of  $A$  [9] if for each open set  $U$  containing  $x$ , the set  $\text{cl}(U) \cap A$  is uncountable.  $A$  is called  $\Omega$ -closed if it contains all its clocondensation points. The complement of an  $\Omega$ -closed set is called  $\Omega$ -open. A subset  $W$  of a space  $(X, \mathfrak{S})$  is  $\Omega$ -open if and only if for each  $x \in W$  there exists an open set  $U$  containing  $x$  such that  $\text{cl}(U) - W$  is countable. The family of all  $\Omega$ -open subsets of a space  $(X, \mathfrak{S})$ , denoted by  $\mathfrak{S}_\Omega$ , forms a topology on  $X$ . Let  $(X, \mathfrak{S})$  be a space and  $A$  be a subset of  $X$ . The  $\Omega$ -interior and  $\Omega$ -closure of a subset  $A$  of a space  $(X, \mathfrak{S})$  is denoted as  $\Omega\text{-cl}(A)$  and  $\Omega\text{-int}(A)$  in the space  $(X, \mathfrak{S}_\Omega)$ . A function  $f : X \rightarrow Y$  is said to be  $\Omega$ -continuous [9] if  $\forall x \in X$  and  $\forall V$  open in  $Y$  containing  $f(x)$ ,  $\exists$  an  $\Omega$ -open subset containing  $x$  such that  $f(U) \subset V$ .

### 3 $\Omega$ – Seprated Sets

**Definition 3.1.** Two nonempty subsets  $A$  and  $B$  of a topological space  $(X, \mathfrak{S})$  are said to be  $\Omega$ -separated if  $A \cap (\Omega\text{-Cl}(B)) = (\Omega\text{-Cl}(A)) \cap B = \phi$ . Obviously, if  $A$  and  $B$  are two  $\Omega$  separated sets, then  $A \cap B = \phi$ . Whenever  $X$  is expressed as a union of two  $\Omega$  separated sets  $A$  and  $B$ , then we say that  $A$  and  $B$  form an  $\Omega$ -separation of  $X$ .

**Remark 3.2.** Let  $(X, \mathfrak{S})$  be a topological space. If  $X$  can be written as union of two  $\Omega$ -separated sets it does not necessarily mean that it can be written as union of two separated sets and vice versa as can be seen from the following examples :

**Example 3.3.** Let  $N$  be the set of natural numbers equipped with the topology  $\mathfrak{S} = \{\phi, X, N_m : m \in N\}$  where  $N_m = \{m, m + 1, m + 2, \dots\}$  then it is clear that  $\mathfrak{S}_\Omega$  is discrete topology on  $N$  as  $N$  is countable and therefore  $X$  has  $\Omega$ -separation since every  $\Omega$ -open set is  $\Omega$ -closed. However,  $X$  has no separation with respect to  $\mathfrak{S}$ .

**Example 3.4.** Let  $R$  be the real line having the topology  $\mathfrak{S} = \{\phi, X, Q\}$ . Evidently,  $\mathfrak{S}_\Omega$  is the co-countable topology. Here  $X$  is neither separated nor  $\Omega$ -separated. Note that  $Q$  is open in  $\mathfrak{S}$  while closed in  $\mathfrak{S}_\Omega$ .

**Example 3.5.** Let  $R$  be the real line equipped with discrete topology then  $\mathfrak{S}_\Omega$  is discrete topology and  $R$  is separated with respect to both the topologies.

**Example 3.6.** Let  $R$  be the real line with point exclusion topology then  $\mathfrak{S}_\Omega$  is cocountable topology therefore  $R$  is separated but not  $\Omega$ -separated.

**Example 3.7.** The two  $\Omega$ -separated sets are always disjoint, since  $A \cap B \subset A \cap (\Omega\text{-Cl}(B)) = \phi$ .

**Theorem 3.8.** For any non – empty subsets  $A$  and  $B$  of a topological space  $(X, \mathfrak{S})$ , the following are equivalent:

- (i)  $A$  and  $B$  are  $\Omega$ -separated.
- (ii) There exist  $\Omega$ -closed sets  $F$  and  $G$  satisfying  $A \subset F \subset (X \sim B)$  and  $B \subset G \subset (X \sim A)$ .
- (iii) There exist  $\Omega$ -open sets  $U$  and  $V$  satisfying  $A \subset U \subset (X \sim B)$  and  $B \subset V \subset (X \sim A)$ .

**Proof.** The Proof is straightforward and hence omitted.

**Theorem 3.9.** Let  $A$  and  $B$  be subsets of a topological space  $(X, \mathfrak{S})$ . If  $A$  and  $B$  are  $\Omega$ -separated,  $\phi \neq C \subset A$  and  $\phi \neq D \subset B$ , then  $C$  and  $D$  are  $\Omega$ -separated.

**Proof.** Since  $A$  and  $B$  are  $\Omega$ -separated sets,  $A \cap (\Omega\text{-Cl}(B)) = \phi$  and  $(\Omega\text{-Cl}(A)) \cap B = \phi$ . By hypothesis  $C \subset A$ , we have  $(\Omega\text{-cl}(C)) \cap B = \phi$ . Similarly, we have  $C \cap (\Omega\text{-Cl}(D)) = \phi$ . Therefore,  $C$  and  $D$  are  $\Omega$ -separated sets.

**Theorem 3.10.** Let  $C$  be a  $\Omega$ -closed subset of a topological space  $(X, \mathfrak{S})$  and let  $A$  and  $B$  be  $\Omega$ -separated sets such that  $C = A \cup B$ , then  $A$  and  $B$  are  $\Omega$ -closed sets.

**Proof.** Let  $C = A \cup B$ , where  $(\Omega\text{-Cl}(A)) \cap B = \phi = A \cap (\Omega\text{-Cl}(B))$ . Now,  $C \cap (\Omega\text{-Cl}(A)) = (A \cup B) \cap (\Omega\text{-Cl}(A)) = A$ . Since the intersection of two  $\Omega$ -closed sets is  $\Omega$ -closed, therefore  $A$  is  $\Omega$ -closed. Similarly, it can be shown that  $B$  is  $\Omega$ -closed.

**Theorem 3.11.** Let  $A$  and  $B$  be non-empty subsets in a topological space  $(X, \mathfrak{S})$ . Then the following statements hold:

- (1) If  $A$  and  $B$  are  $\Omega$ -separated and  $P \subset A, Q \subset B$ , then  $P$  and  $Q$  are also  $\Omega$ -separated.
- (2) If  $A \cap B = \phi$  such that  $A$  and  $B$  are  $\Omega$ -closed ( $\Omega$ -open), then  $A$  and  $B$  are  $\Omega$ -separated.
- (3) If  $A$  and  $B$  are  $\Omega$ -closed ( $\Omega$ -open) and  $H = A \cap (X \sim B)$  and  $G = B \cap (X \sim A)$ , then  $H$  and  $G$  are  $\Omega$ -separated.

**Proof.** (1) Since  $P \subset A, (\Omega\text{-cl}(P)) \subset (\Omega\text{-cl}(A))$ . Then  $B \cap (\Omega\text{-cl}(A)) = \phi$  implies  $Q \cap (\Omega\text{-cl}(A)) = \phi$  and  $Q \cap (\Omega\text{-cl}(P)) = \phi$ . Similarly  $P \cap (\Omega\text{-cl}(Q)) = \phi$ . Hence  $P$  and  $Q$  are  $\Omega$ -separated.

(2) Since  $A = (\Omega\text{-cl}(A)), B = (\Omega\text{-cl}(B))$  and  $A \cap B = \phi, (\Omega\text{-cl}(A)) \cap B = \phi$  and  $(\Omega\text{-cl}(B)) \cap A = \phi$ . Hence  $A$  and  $B$  are  $\Omega$ -separated sets. If  $A$  and  $B$  are  $\Omega$ -open, then their complements are  $\Omega$ -closed.

(3) If  $A$  and  $B$  are  $\Omega$ -open, then  $X-A$  and  $X-B$  are  $\Omega$ -closed. Since  $H \subset X \sim B, (\Omega\text{-cl}(H)) \subset (\Omega\text{-cl}(X \sim B)) = X \sim B$  and so  $(\Omega\text{-cl}(H)) \cap B = \phi$ . Thus  $G \cap \Omega\text{-Cl}(H) = \phi$ . Similarly,  $H \cap (\Omega\text{-cl}(G)) = \phi$ . Hence  $H$  and  $G$  are  $\Omega$ -separated sets.

**Theorem 3.12.** *Two sets  $A$  and  $B$  of a topological space  $(X, \mathfrak{S})$  are  $\Omega$ -separated if and only if there exist  $\Omega$ -open sets  $U$  and  $V$  such that  $A \subset U, B \subset V, A \cap V = \phi$  and  $B \cap U = \phi$ .*

**Proof.** Let  $A$  and  $B$  be  $\Omega$ -separated sets. Let  $V = X \sim (\Omega\text{-cl}(A))$  and  $U = X \sim (\Omega\text{-cl}(B))$ . Then  $U, V$  are  $\Omega$ -open sets such that  $A \subset U, B \subset V, A \cap V = \phi$  and  $B \cap U = \phi$ . Conversely, let  $U, V$  be two  $\Omega$ -open subsets of  $X$  satisfying  $A \subset U, B \subset V, A \cap V = \phi$  and  $B \cap U = \phi$ . Since  $X \sim V$  and  $X \sim U$  are  $\Omega$ -closed sets,  $(\Omega\text{-cl}(A)) \subset X \sim V \subset X \sim B$  and  $(\Omega\text{-cl}(B)) \subset X \sim U \subset X \sim A$ . Thus  $(\Omega\text{-cl}(A)) \cap B = \phi$  and  $(\Omega\text{-cl}(B)) \cap A = \phi$ .

**Theorem 3.13.** *Let  $A$  and  $B$  be non-empty disjoint subsets of a topological space  $(X, \mathfrak{S})$  and let  $E$  be a subset of  $X$  such that  $E = A \cup B$ . Then  $A$  and  $B$  are  $\Omega$ -separated in  $X$  if and only if each of  $A$  and  $B$  are  $\Omega$ -closed ( $\Omega$ -open) in  $E$ .*

**Proof.** Let  $A$  and  $B$  be  $\Omega$ -separated sets in  $X$ . Then  $A \cap (\Omega\text{-cl}(B)) = \phi$  which implies that  $(\Omega\text{-cl}(B)) \subset (X \sim A)$  i.e.  $B$  contains all  $\Omega$ -limit points of  $B$  which are in  $A \cup B = E$ . Hence  $B$  is  $\Omega$ -closed in  $E$ . Similarly  $A$  is also  $\Omega$ -closed in  $E$ .

**Theorem 3.14.** *Let  $(X, \mathfrak{S})$  be a topological space. If  $A$  and  $B$  are  $\Omega$ -separations of  $X$  itself, then  $A$  and  $B$  are  $\Omega$ -closed sets of  $(X, \mathfrak{S})$ .*

**Proof.** Since  $A$  and  $B$  are  $\Omega$ -separated,  $A \cap (\Omega\text{-cl}(B)) = (\Omega\text{-cl}(A)) \cap B = \phi$ . Then  $A \cap (\Omega\text{-cl}(B)) = \phi$  if and only if  $B$  is  $\Omega$ -closed in  $A \cup B = X$ . Similarly, we can show that  $A$  is  $\Omega$ -closed in  $X$ .

**Theorem 3.15.**  *$X$  has  $\Omega$  separation if and only if  $X$  has a subset which is both  $\Omega$ -open and  $\Omega$ -closed.*

**Proof.** Let  $A$  be such subset of  $X$  then  $X \sim A$  is both  $\Omega$ -open and  $\Omega$ -closed such that  $A \cap (X \sim A) = \phi$  while  $A \cup (X \sim A) = X$ . Conversely, let  $X = A \cup B$  such that both  $A$  and  $B$  are disjoint, nonempty and  $\Omega$ -open. Then  $A$  is  $\Omega$ -closed also.

### 4 Properties Of $\Omega$ – Connected Spaces

In this section, we introduce and study  $\Omega$ -connected spaces and also investigate some of their basic properties.

**Definition 4.1.** A subset  $A$  of a topological space  $(X, \mathfrak{S})$  is said to be  $\Omega$ -connected if it cannot be expressed as the union of two  $\Omega$ -separated sets. Otherwise, the set  $A$  is called  $\Omega$ -disconnected.

**Example 4.2.** Let  $N$  be the set of natural numbers equipped with the topology  $\mathfrak{S} = \{\phi, X, N_m : m \in N\}$  where  $N_m = \{m, m+1, m+2, \dots\}$  then  $\mathfrak{S}_\Omega$  is discrete topology as  $N$  is countable and therefore disconnected as every  $\Omega$ -open set is  $\Omega$ -closed whereas  $X$  is  $\mathfrak{S}$ -connected.

**Example 4.3.** Let  $R$  be the real line having the topology  $\mathfrak{S} = \{\phi, X, Q\}$  then  $\mathfrak{S}_\Omega$  is cocountable topology. Here both  $\mathfrak{S}$  and  $\mathfrak{S}_\Omega$  are connected. Note that  $Q$  is open in  $\mathfrak{S}$  while closed in  $\mathfrak{S}_\Omega$ .

**Example 4.4.** Let  $R$  be the real line equipped with real topology then  $\mathfrak{S}_\Omega$  is also discrete topology and both the topologies are disconnected.

**Example 4.5.** Let  $R$  be the real line with point exclusion topology then  $\mathfrak{S}_\Omega$  is cocountable topology therefore  $R$  is disconnected but  $\Omega$ -connected.

**Theorem 4.6.** *Let  $A \subset B \cup C$  such that  $A$  is a nonempty  $\Omega$ -connected set in a topological space  $(X, \mathfrak{S})$  and  $B, C$  be  $\Omega$ -separated sets. Then only one of the following conditions holds:*

- (a)  $A \subset B$  and  $A \cap C = \phi$ .
- (b)  $A \subset C$  and  $A \cap B = \phi$ .

**Proof.** If  $A \cap C = \phi$  then  $A \subset B$ . Similarly, if  $A \cap B = \phi$ , then  $A \subset C$ . Since  $A \subset B \cap C$ , then both  $A \cap B = \phi$  and  $A \cap C = \phi$  cannot hold simultaneously. Conversely, suppose that  $A \cap B \neq \phi$  and  $A \cap C \neq \phi$ , then,  $A \cap B$  and  $A \cap C$  are  $\Omega$ -separated sets such that  $A = (A \cap B) \cup (A \cap C)$  which contradicts with the  $\Omega$ -connectedness of  $A$ . Hence only one of the conditions (a) and (b) must hold.

**Theorem 4.7.** *If  $A$  and  $B$  are  $\Omega$ -separated sets in a topological space  $(X, \mathfrak{S})$  such that  $X=A \cup B$  and if an  $\Omega$ -connected set  $S$  is contained in  $A \cup B$ , then either  $S \subset A$  or  $S \subset B$ .*

**Proof.** We are given that  $X = A \cup B$ . Now,  $S = X \cap S = (A \cup B) \cap S = (S \cap A) \cup (S \cap B)$ . Since  $(S \cap A) \subset A$  and  $(S \cap B) \subset B$  therefore they form separation of  $S$ . Since  $S$  is  $\Omega$ -connected, therefore, either  $(S \cap A)$  is empty or  $(S \cap B)$  is empty that is either  $S \subset B$  or  $S \subset A$ .

**Theorem 4.8.** *Let  $B$  be a subset of a topological space  $(X, \mathfrak{S})$  such that there exists a  $\Omega$ -connected set  $A$  satisfying  $A \subset B \subset (\Omega\text{-cl}(A))$  then  $B$  is also  $\Omega$ -connected.*

**Proof.** Let  $B = P \cup Q$ , where  $P$  and  $Q$  are  $\Omega$ -separated sets. Then either  $A \subset P$  or  $A \subset Q$  and hence either  $B \subset (\Omega\text{-cl}(A)) \subset (\Omega\text{-cl}(P)) \subset (X \sim Q)$  or  $B \subset (X \sim P)$ . Therefore either  $P = \phi$  or  $Q = \phi$ .

**Theorem 4.9.** *If  $A$  is  $\Omega$ -connected set of a topological space  $(X, \mathfrak{S})$ , then so is  $(\Omega\text{-cl}(A))$ .*

**Proof.** Follows from **Theorem 4.8**.

**Theorem 4.10.** *If  $\{C_\alpha : \alpha \in \Delta\}$  is a family of  $\Omega$ -connected sets in a topological space  $(X, \mathfrak{S})$  satisfying the property that any two of them are not  $\Omega$ -separated, then  $C = \bigcup_{\alpha \in \Delta} C_\alpha$  is  $\Omega$ -connected.*

**Proof.** Let  $C = A \cup B$ , where  $A$  and  $B$  are  $\Omega$ -separated sets. Then for each  $\alpha \in \Delta$  either  $C_\alpha \subset A$  or  $C_\alpha \subset B$ . Since no two members of the family  $\{C_\alpha : \alpha \in \Delta\}$  are  $\Omega$ -separated, either  $C_\alpha \subset A$  for each  $\alpha \in \Delta$  or  $C_\alpha \subset B$  for each  $\alpha \in \Delta$ . So either  $B = \phi$  or  $A = \phi$ .

**Theorem 4.11.** *If  $C = \bigcup_{\alpha \in \Delta} C_\alpha$ , where each  $C_\alpha$  is  $\Omega$ -connected set in a topological space  $(X, \mathfrak{S})$  and also  $C_\alpha \cap C_{\alpha'} \neq \phi$  for  $\alpha, \alpha' \in \Delta$ , then  $C$  is  $\Omega$ -connected.*

**Proof.** Obvious and hence omitted.

**Theorem 4.12.** *If  $C = \bigcup_{\alpha \in \Delta} C_\alpha$ , where each  $C_\alpha$  is  $\Omega$ -connected in a topological space  $(X, \mathfrak{S})$  and  $\bigcap_{\alpha \in \Delta} C_\alpha \neq \phi$  for each  $\alpha \in \Delta$ , then  $C$  is  $\Omega$ -connected.*

**Proof.** Suppose that  $C$  is not  $\Omega$ -connected. Let  $C = A \cup B$ , where  $A$  and  $B$  are  $\Omega$ -separated sets. Then for each  $\alpha \in \Delta$  either  $C_\alpha \subset A$  or  $C_\alpha \subset B$ . Since  $\bigcap_{\alpha \in \Delta} C_\alpha \neq \phi$ , we have a point  $x \in \bigcap_{\alpha \in \Delta} C_\alpha$ . Then either  $x \in A$  or  $x \in B$ . Let  $x \in A$ . Since  $x \in C_\alpha$  for each  $\alpha \in \Delta$ , then  $C_\alpha \in A$  for each  $\alpha \in \Delta$  which means that  $B$  contains no element of  $C$  as  $A$  and  $B$  are disjoint. Hence  $B$  is empty. Similarly if  $x \in B$  then due to same reason  $A$  will be empty. Thus  $C$  is  $\Omega$ -connected.

**Theorem 4.13.** *For a topological space  $(X, \mathfrak{S})$ , the following statements are equivalent:*

- (1)  $X$  is  $\Omega$ -connected.
- (2)  $X$  cannot be expressed as the union of two nonempty disjoint  $\Omega$ -open sets.
- (3)  $X$  contains no nonempty proper subset which is both  $\Omega$ -open and  $\Omega$ -closed.

**Proof.** (1)  $\Rightarrow$  (2): Suppose that  $X$  is  $\Omega$ -connected and if  $X$  can be expressed as the union of two nonempty disjoint sets  $A$  and  $B$  such that  $A$  and  $B$  are  $\Omega$ -open sets. Consequently  $A \subset X \sim B$ . Then  $(\Omega\text{-cl}(A)) \subset \Omega\text{-cl}(X \sim B) = X \sim B$ . Therefore,  $(\Omega\text{-cl}(A)) \cap B = \phi$ . Similarly we can prove  $A \cap (\Omega\text{-cl}(B)) = \phi$ . This is a contradiction to the fact that  $X$  is  $\Omega$ -connected. Therefore,  $X$  cannot be expressed as the union of two nonempty disjoint  $\Omega$ -open sets.

(2)  $\Rightarrow$  (3): Suppose that  $X$  cannot be expressed as the union of two nonempty disjoint sets  $A$  and  $B$  such that both  $A$  and  $B$  are  $\Omega$ -open sets. If  $X$  contains a nonempty proper subset  $A$  which is both  $\Omega$ -open and  $\Omega$ -closed. Then  $X = A \cup (X \sim A)$ . Hence  $A$  and  $X \sim A$  are disjoint  $\Omega$ -open sets whose union is  $X$ . This is the contradiction to our assumption. Hence,  $X$  contains no nonempty proper subset which is both  $\Omega$ -open and  $\Omega$ -closed.

(3)  $\Rightarrow$  (1): Suppose that  $X$  contains no nonempty proper subset which is both  $\Omega$ -open and  $\Omega$ -closed and  $X$  is not  $\Omega$ -connected. Then  $X$  can be expressed as the union of two nonempty disjoint sets  $A$  and  $B$  such that  $(A \cap (\Omega\text{-cl}(B))) \cup ((\Omega\text{-cl}(A)) \cap B) = \phi$ . Since  $A \cap B = \phi$ ,  $A = X \sim B$  and  $B = X \sim A$ . Since  $(\Omega\text{-cl}(A)) \cap B = \phi$ ,  $(\Omega\text{-cl}(A)) \subset X \sim B$ . Hence  $(\Omega\text{-cl}(A)) \subset A$ . Therefore,  $A$  is  $\Omega$ -closed. Similarly,  $B$  is  $\Omega$ -closed. Since  $A = X \sim B$ ,  $A$  is  $\Omega$ -open. Therefore, there exists a non-empty proper subset  $A$  which is both  $\Omega$ -open and  $\Omega$ -closed. This is a contradiction to our assumption. Therefore,  $X$  is  $\Omega$ -connected.

**Theorem 4.14.** *A topological space  $(X, \mathfrak{S})$  is  $\Omega$ -connected if and only if for every pair of points  $x, y$  in  $X$ , there is a  $\Omega$ -connected subset of  $X$  which contains both  $x$  and  $y$ .*

**Proof.** The necessity is immediate since the  $\Omega$ -connected space itself contains these two points. For the sufficiency, suppose that for any two points  $x$  and  $y$ , there is a  $\Omega$ -connected subset  $C_{x,y}$  of  $X$  such that  $x, y \in C_{x,y}$ . Let  $a \in X$  be a fixed point and consider the family  $\{C_{a,x} : x \in X\}$  of all  $\Omega$ -connected subsets of  $X$  which contain the points  $a$  and  $x$ . Then  $X = \bigcup_{x \in X} C_{a,x}$  and  $\bigcap_{x \in X} C_{a,x} \neq \emptyset$ . Therefore  $X$  is  $\Omega$ -connected.

**Theorem 4.15.** *For a topological space  $(X, \mathfrak{S})$  the following are equivalent:*

- (1).  $(X, \mathfrak{S})$  is  $\Omega$ -connected
- (2). The only subsets of  $(X, \mathfrak{S})$  which are both  $\Omega$ -open and  $\Omega$ -closed are the empty set  $\emptyset$  and  $X$ .
- (3). Each  $\Omega$ -continuous map of  $(X, \mathfrak{S})$  into a discrete space  $(Y, \sigma)$  with at least two points is a constant map.

**Proof.** (1)  $\Rightarrow$  (2) : Let  $G$  be an  $\Omega$ -open and  $\Omega$ -closed subset of  $(X, \mathfrak{S})$ . Then  $X \sim G$  is also both  $\Omega$ -open and  $\Omega$ -closed. Then  $X = G \cup (X \sim G)$  a disjoint union of two non-empty  $\Omega$ -open sets which contradicts the fact that  $(X, \mathfrak{S})$  is  $\Omega$ -connected. Hence  $G = \emptyset$  or  $X$ .

(2)  $\Rightarrow$  (1): Suppose that  $X = A \cup B$  where  $A$  and  $B$  are disjoint non-empty  $\Omega$ -open subsets of  $(X, \mathfrak{S})$ . Since  $A = X - B$ , then  $A$  is both  $\Omega$ -open and  $\Omega$ -closed. By assumption  $A = \emptyset$  or  $X$ , which is a contradiction. Hence  $(X, \mathfrak{S})$  is  $\Omega$ -connected.

(2)  $\Rightarrow$  (3): Let  $f : (X, \mathfrak{S}) \rightarrow (Y, \sigma)$  be a  $\Omega$ -continuous map, where  $(Y, \sigma)$  is discrete space with at least two points. Then  $f^{-1}\{y\}$  is  $\Omega$ -closed and  $\Omega$ -open for each  $y \in Y$ . By assumption,  $f^{-1}\{y\} = \emptyset$  or  $X$  for each  $y \in Y$ . If  $f^{-1}\{y\} = \emptyset$  for each  $y \in Y$ , then  $f$  fails to be a map. Therefore there exists a point say  $z \in Y$  such that  $f^{-1}\{z\} = X$ . This shows that  $f$  is a constant map.

(3)  $\Rightarrow$  (2): Let  $G$  be both  $\Omega$ -open and  $\Omega$ -closed in  $(X, \mathfrak{S})$ . Suppose  $G \neq \emptyset$ . Let  $f : (X, \mathfrak{S}) \rightarrow (Y, \sigma)$  be a  $\Omega$ -continuous map defined by  $f(G) = a$  and  $f(X - G) = b$  where  $a \neq b$  and  $a, b \in Y$ . By assumption,  $f$  is constant so  $G = X$ .

**Theorem 4.16.** *Every  $\Omega$ -connected space is connected.*

**Proof.** Let  $X$  be  $\Omega$ -connected and if possible let  $X$  be disconnected then there is a proper subset  $A$  of  $X$  which is both open and closed. But such a set is also both  $\Omega$ -open and  $\Omega$ -closed which is a contradiction thus  $\Omega$ -connected is connected.

**Theorem 4.17.** *Let  $f : (X, \mathfrak{S}) \rightarrow (Y, \sigma)$  be an  $\Omega$ -continuous surjection and  $(X, \mathfrak{S})$  be  $\Omega$ -connected, then  $(Y, \sigma)$  is connected.*

**Proof.** Suppose that  $(Y, \sigma)$  is not connected. Let  $Y = A \cup B$  where  $A$  and  $B$  are disjoint non-empty open subsets in  $(Y, \sigma)$ . Since  $f$  is  $\Omega$ -continuous,  $X = f^{-1}(A) \cup f^{-1}(B)$ , where  $f^{-1}(A)$  and  $f^{-1}(B)$  are disjoint non-empty  $\Omega$ -open subsets in  $(X, \mathfrak{S})$ . This contradicts the fact that  $(X, \mathfrak{S})$  is  $\Omega$ -connected. Hence  $(Y, \sigma)$  is connected.

**Definition 4.18.** A function  $f : (X, \mathfrak{S}) \rightarrow (Y, \sigma)$  is said to be strongly  $\Omega$ -continuous function if inverse image of every  $\Omega$ -closed set is closed.

**Definition 4.19.** A function  $f : (X, \mathfrak{S}) \rightarrow (Y, \sigma)$  is said to be  $\Omega$ -irresolute function if inverse image of every  $\Omega$ -closed set is  $\Omega$ -closed.

The Proofs of the following theorem are straightforward and hence omitted.

**Theorem 4.20.** *Let  $f : (X, \mathfrak{S}) \rightarrow (Y, \sigma)$  be a  $\Omega$ -irresolute surjection and  $(X, \mathfrak{S})$  is  $\Omega$ -connected, then  $(Y, \sigma)$  is  $\Omega$ -connected.*

**Theorem 4.21.** *The image of a connected space under strongly  $\Omega$ -continuous map is  $\Omega$ -connected.*

**Theorem 4.22.** *If  $(X, \mathfrak{S})$  is  $\Omega$ -disconnected and  $\mathfrak{S}'$  is finer than  $\mathfrak{S}$  then  $(X, \mathfrak{S}')$  is  $\Omega$ -disconnected.*

**Theorem 4.23.** *If  $(X, \mathfrak{S})$  is  $\Omega$ -connected and  $\mathfrak{S}'$  is coarser than  $\mathfrak{S}$  then  $(X, \mathfrak{S}')$  is  $\Omega$ -connected.*

**Theorem 4.24.** *If every two points of  $E \subset X$  are contained in some  $\Omega$ -connected space of  $E$  then  $E$  is  $\Omega$ -connected subset of  $X$ .*

**Proof.** Let  $E$  be not  $\Omega$ -connected then for some  $A, B \subset X$ ,  $E = A \cup B$  such that  $\Omega\text{-cl}(A) \cap B = \phi = A \cap (\Omega\text{-cl}(B))$ . Since both  $A$  and  $B$  are nonempty let  $a \in A$  and  $b \in B$  for some  $a, b \in E$  then there exists a  $\Omega$ -connected subset  $F$  of  $E$  such that  $a, b \in F$ . Since  $F \subset A \cup B$  either  $F \subset A$  or  $F \subset B$ . Without loss of generality let we assume that  $F \subset A$  then  $a, b \in A$  which means that  $A \cap B \neq \phi$  which is a contradiction. Hence  $E$  has to be  $\Omega$ -connected.

## 5 Locally $\Omega$ -Connected

**Definition 5.1.** A subset  $A$  of a topological space  $(X, \mathfrak{S})$  is said to be locally  $\Omega$ -connected at  $x \in X$  if for every  $\Omega$ -open set  $U$  containing  $x$  there exists a  $\Omega$ -open and  $\Omega$ -connected set  $V$  containing  $x$  and contained in  $U$ . If  $X$  is locally  $\Omega$ -connected at each of its points then  $X$  is said to be locally  $\Omega$ -connected.

**Example 5.2.** Let  $\mathbb{R}$  be the set of real numbers with usual topology then  $\mathbb{R}$  is  $\Omega$ -connected and locally  $\Omega$ -connected as well.

**Example 5.3.** The subspace  $(1,2) \cup (2,3)$  of the real line is  $\Omega$  disconnected but locally  $\Omega$ -connected.

**Example 5.4.** In discrete topology  $\mathbb{R}$  is  $\Omega$ -disconnected but locally  $\Omega$ -connected.

**Definition 5.5.** A function  $f : (X, \mathfrak{S}) \rightarrow (Y; \sigma)$  is said to be  $o\Omega$ -open function if image of every open set in  $X$  is  $\Omega$ -open in  $Y$ .

**Definition 5.6.** A function  $f : (X, \mathfrak{S}) \rightarrow (Y; \sigma)$  is said to be  $\Omega$ -open function if image of every  $\Omega$ -open set in  $X$  is open in  $Y$ .

**Definition 5.7.** A function  $f : (X, \mathfrak{S}) \rightarrow (Y; \sigma)$  is said to be  $\Omega\Omega$ -open function if image of every  $\Omega$ -open set in  $X$  is  $\Omega$ -open in  $Y$ .

**Theorem 5.8.** *The image of a locally  $\Omega$ -connected space under  $\Omega$ -continuous,  $\Omega$ -open map is locally connected.*

**Proof.** Let  $f : (X, \mathfrak{S}) \rightarrow (Y; \sigma)$  be a  $\Omega$ -continuous,  $\Omega$ -open map of  $X$  into  $Y$ . Let  $y \in Y$  then there exists  $x \in X$  such that  $f(x) = y$ . Let  $V_y$  be an open set containing  $y$  then  $f^{-1}(V_y)$  is a  $\Omega$ -open set containing  $x$ . Since  $X$  is locally  $\Omega$ -connected it contains a  $\Omega$ -open-set  $U_y$  which is  $\Omega$ -connected. This implies that  $y \in f(U_y)$  such that  $f(U_y)$  is open (as  $f$  is  $\Omega$ -open) and connected (as  $f$  is  $\Omega$ -continuous) and  $f(U_y)$  is contained in  $V_y$ . Hence  $Y$  is locally connected.

**Theorem 5.9.** *The image of a locally  $\Omega$ -connected space under  $\Omega$ -irresolute,  $\Omega\Omega$ -open map is locally  $\Omega$ -connected.*

**Proof.** Let  $f : (X, \mathfrak{S}) \rightarrow (Y; \sigma)$  be an  $\Omega\Omega$ -irresolute,  $\Omega$ -open map of  $X$  into  $Y$ . Let  $y \in Y$  then there exists  $x \in X$  such that  $f(x) = y$ . Let  $V_y$  be an  $\Omega$ -open set containing  $y$  then  $f^{-1}(V_y)$  is an  $\Omega$ -open set containing  $x$ . Since  $X$  is locally  $\Omega$ -connected it contains a  $\Omega$ -open set  $U_y$  which is  $\Omega$ -connected and implies that  $y \in f(U_y)$  such that  $f(U_y)$  is  $\Omega$ -open (as  $f$  is  $\Omega$ -open) and  $\Omega$ -connected (as  $f$  is  $\Omega$ -irresolute) and  $f(U_y)$  is contained in  $V_y$ . Hence  $Y$  is locally  $\Omega$ -connected.

**Theorem 5.10.** *The image of a locally connected space under strongly  $\Omega$ -continuous,  $o\Omega$ -open map is locally  $\Omega$ -connected.*

**Proof.** Let  $f : (X, \mathfrak{S}) \rightarrow (Y; \sigma)$  be a strongly  $\Omega$ -continuous,  $o\Omega$ -open map of  $X$  into  $Y$ . Let  $y \in Y$  then there exists  $x \in X$  such that  $f(x) = y$ . Let  $V_y$  be a  $\Omega$ -open set containing  $y$  then  $f^{-1}(V_y)$  is an open set containing  $x$ . Since  $X$  is locally connected it contains an open set  $U_y$  which is connected. This implies that  $y \in f(U_y)$  such that  $f(U_y)$  is  $\Omega$ -open (as  $f$  is  $o\Omega$ -open) and  $\Omega$ -connected (as  $f$  is strongly  $\Omega$ -continuous) and  $f(U_y)$  is contained in  $V_y$ . Hence  $Y$  is locally  $\Omega$ -connected.

**Theorem 5.11.** *A  $\Omega$ -open subset of a locally  $\Omega$ -connected space is locally  $\Omega$ -connected.*

**Theorem 5.12.** *A space  $(X, \mathfrak{S})$  is locally  $\Omega$ -connected if and only if it has a basis consisting of  $\Omega$ -connected  $\Omega$ -open sets.*

**Proof.** Follows from the definition of locally  $\Omega$ -connectedness.

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