

Generalized r – Minkowski formula on weighted manifolds

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Abstract In this paper we derive an integral formula for hypersurfaces embedded in weighted manifolds involving the weighted higher order mean curvatures σ_k^∞ of the hypersurface and the weighted Newton transformations T_k^∞ (see [11]). This formula generalizes the classical r –Minkowski integral formula on Riemannian manifolds.

1 Introduction

Integral formulas are useful tools for solving many problems in Riemannian geometry, such as Alexandrov’s theorem or the characterization of certain hypersurfaces (see [4, 3, 20]) and references therein.

Let $x : M^n \longrightarrow \overline{M}^{n+1}$ be a closed oriented hypersurface immersed into a space form \overline{M}^{n+1} with unit normal vector field N . Then we have for $1 \leq r \leq n$:

$$\int_{M^n} H_{r-1} dv + \int_{M^n} \langle Y, N \rangle . H_r dv = 0, \quad (1.1)$$

where Y is a conformal vector field, and H_r is the higher order mean curvature of the hypersurface.

Higher order Minkowski formulae were first obtained by Hsiung [15] in Euclidean space, and by Bivens [9] in the Euclidean sphere and hyperbolic space.

Many generalizations of the previous results have been investigated in the case where the ambient space is not a space form and in other contexts, see for instance [3, 4, 9, 16, 17, 20].

In a series of recent papers, the first author together with M. Benalili [1, 2] obtained a series of integral formulas on weighted manifolds . The idea is to compute the divergence of certain vector fields and applying the divergence theorem.

In this paper, using the weighed symmetric functions σ_k^∞ and the weighted Newton transformations T_k^∞ introduced by J. S. Case [11], we derive some new integral formulae on manifolds with density. We give also some applications and special cases.

2 Preliminaries

In this section, we will fix the notations and recall some definitions and basic results of weighted manifolds and the weighted Newton transformations. For more details, see [2, 11, 12, 13].

A weighted manifold $(\overline{M}, \langle, \rangle, dv_f)$ is a Riemannian manifold \overline{M} endowed with a weighted volume form $dv_f = e^{-f} dv$, where f is a real-valued smooth function on \overline{M} , and dv is the Riemannian volume form associated with the metric \langle, \rangle .

Let \overline{M}_f^{n+1} be an $(n + 1)$ –dimensional oriented weighted Riemannian manifold, and $\psi : M^n \longrightarrow \overline{M}_f^{n+1}$ be an isometrically immersed hypersurface with unit normal vector field N in the normal bundle NM^n . It’s Weingarten operator A is defined by

$$AX = -(\overline{\nabla}_X N)^\top,$$

where $\bar{\nabla}$ is the Levi-Civita connection on \bar{M}_f^{n+1} , and $X \in \mathfrak{X}(M^n)$.

By the Codazzi equation, we can see that the normal component of the curvature tensor \bar{R} of \bar{M}_f^{n+1} is given in terms of A by

$$\langle \bar{R}(U, V)W, N \rangle = \langle (\bar{\nabla}_V A)U - (\bar{\nabla}_U A)V, W \rangle,$$

where $U, V, W \in \mathfrak{X}(M^n)$. In particular if the ambient space has constant sectional curvature, then we have

$$(\bar{\nabla}_V A)U = (\bar{\nabla}_U A)V.$$

It is well known that A is a linear self adjoint operator and at each point $p \in M^n$, its eigenvalues μ_1, \dots, μ_n are the principal curvatures of M^n .

The weighted elementary symmetric polynomial $\sigma_k^\infty : \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}$ are defined recursively by (see [11])

$$\begin{cases} \sigma_0^\infty(u, \mu) = 1, \\ k\sigma_k^\infty(u, \mu) = u\sigma_{k-1}^\infty(u, \mu) + \sum_{j=0}^{k-1} \sum_{i=1}^n (-1)^j \sigma_{k-1-j}^\infty(u, \mu) \mu_i^{j+1} & \text{for } 1 \leq k \leq n, \\ \sigma_k^\infty(u, \mu) = 0 & \text{for } k > n, \end{cases} \quad (2.1)$$

where $u \in \mathbb{R}$ and $\mu = (\mu_1, \dots, \mu_n) \in \mathbb{R}^n$. The weighted elementary symmetric functions $\sigma_k^\infty(u, A)$ of A are defined by

$$\sigma_k^\infty(u, A) = \sigma_k^\infty(u, \mu),$$

where μ_1, \dots, μ_n are the eigenvalues of A .

In particular, for $u = 0$, $\sigma_k^\infty(0, A) = \sigma_k(A)$ is the classical elementary symmetric functions defined in [19].

Associate to A , we can define the weighted Newton transformations $T_k^\infty(\mu_0, A)$ by

$$\begin{cases} T_0^\infty(u, A) = I, \\ T_k^\infty(u, A) = \sigma_k^\infty(u, A)I - AT_{k-1}^\infty(u, A) & \text{for } k \geq 1. \end{cases}$$

This is equivalent to

$$T_k^\infty(u, A) = \sum_{i=0}^k (-1)^i \sigma_{k-i}^\infty(u, A) A^i. \quad (2.2)$$

If $u = 0$, then $T_k^\infty(0, A) = T_k(A)$ is just the classical Newton transformations introduced and studied by R. C. Reilly [19].

Since A is self-adjoint operator, then T_k^∞ are self-adjoint as well and their eigenvectors are the same as those of A , and we have the following properties, whose proof can be found in [11].

Proposition 2.1. *For any reals $u_1, u_2 \in \mathbb{R}$ and $\mu \in \mathbb{R}^n$, we have*

$$\sigma_k^\infty(u_1 + u_2, \mu) = \sum_{i=0}^k \frac{u_1^i}{i!} \sigma_{k-i}^\infty(u_2, \mu).$$

In particular

$$\sigma_k^\infty(u_1, \mu) = \sum_{i=0}^k \frac{u_1^i}{i!} \sigma_{k-i}^\infty(\mu),$$

and

$$\text{trace}(AT_k^\infty(u, \mu)) = (k+1)\sigma_{k+1}^\infty(u, \mu) - u\sigma_k^\infty(u, \mu).$$

The i^{th} eigenvalue of $T_k^\infty(u, \mu)$ is equal to $\sigma_{k,i}^\infty(u, \mu)$, where

$$\sigma_{k,i}^\infty(u, \mu) = \sigma_k^\infty(u, \hat{\mu}_i) = \sigma_k^\infty(u, \mu) - \mu_i \sigma_{k-1,i}^\infty(u, \mu),$$

where $\mu = (\mu_1, \dots, \mu_n)$, and μ_1, \dots, μ_n are the eigenvalues of A .

Definition 2.2. Let M be an immersed hypersurface of \overline{M}_f with shape operator A with relation to an unit normal vector field N . The weighted k -curvature σ_k^∞ of the hypersurface M is defined by,

$$\sigma_k^\infty = \sigma_k^\infty(u, A) \quad \text{for } u = \langle \overline{\nabla} f, N \rangle.$$

The weighted Newton transformations will be denoted by,

$$T_k^\infty = T_k^\infty(u, A) \quad \text{for } u = \langle \overline{\nabla} f, N \rangle.$$

And we have

$$T_k^\infty = \begin{cases} I, & \text{for } k = 0, \\ \sigma_k^\infty I - AT_{k-1}^\infty, & \text{for } k \geq 1. \end{cases}$$

In particular, for $k = 1$, we get

$$\sigma_1^\infty = H_f = \sigma_1 + \langle \overline{\nabla} f, N \rangle,$$

which is the classical definition of the weighted mean curvature of the hypersurface M studied by Gromov [14].

The divergence of the weighted Newton transformations is define by

$$\operatorname{div}(T_k^\infty) = \operatorname{trace}(\overline{\nabla} T_k^\infty) = \sum_{i=1}^n (\overline{\nabla}_{e_i} T_k^\infty)(e_i),$$

where $\{e_1, \dots, e_n\}$ is a local orthonormal frame on M^n .

Before to start our computations, we need the following results

Proposition 2.3. 1. For $0 \leq k \leq n$, we have

$$T_k^\infty = \sum_{j=0}^k \frac{u^j}{j!} T_{k-j}, \quad \text{where } u = \langle \overline{\nabla} f, N \rangle. \quad (2.3)$$

2. The divergence of the weighted Newton transformations is given by

$$\operatorname{div} T_0^\infty = 0,$$

and for $1 \leq k \leq n$

$$\operatorname{div} T_k^\infty = T_{k-1}^\infty \circ \nabla u + \sum_{j=1}^k \frac{u^j}{j!} \operatorname{div} T_{k-j},$$

where $\operatorname{div} T_{k-j}$ is given by (3.3) in [4].

In particular, if \overline{M}^{n+1} has constant sectional curvature, then we have

$$\operatorname{div} T_k^\infty = \sum_{j=0}^{k-1} (-1)^j \sigma_{k-1-j}^\infty A^j \circ \nabla u. \quad (2.4)$$

Proof. 1. The relation (2.3) can be deduced directly from the definition of T_k^∞ .

In fact we have for $0 \leq k \leq n$

$$\begin{aligned} T_k^\infty &= \sum_{i=0}^k (-1)^i \sigma_{k-i}^\infty A^i, \\ &= \sum_{i=0}^k \sum_{l=0}^{k-j} (-1)^j \frac{u^l}{l!} \sigma_{k-j-l}^\infty A^j, \\ &= \sum_{l=0}^k \frac{u^l}{l!} T_{k-l}. \end{aligned}$$

Where the first equality combines equation (2.3) with the definition of T_k^∞ , the second equality switches the order of the summation, and the third equality uses the definition of the (un-weighted) Newton transformations.

2. For $0 \leq k \leq n$, we have

$$\begin{aligned}
 \operatorname{div} T_k^\infty &= \operatorname{tr} (\nabla T_k^\infty), \\
 &= \sum_{i=1}^n \bar{\nabla}_{e_i} (T_k^\infty) (e_i), \\
 &= \sum_{i=1}^n \bar{\nabla}_{e_i} \left(\sum_{j=0}^k \left(\frac{u^j}{j!} T_{k-j} \right) \right) (e_i), \\
 &= \sum_{i=1}^n \bar{\nabla}_{e_i} \left(\sum_{j=0}^k \left(\frac{u^j}{j!} T_{k-j} \right) \right) (e_i), \\
 &= \sum_{i=1}^n \bar{\nabla}_{e_i} \left(\sum_{j=0}^k \left(\frac{u^j}{j!} T_{k-j} \right) \right) (e_i), \\
 &= \sum_{i=1}^n \sum_{j=0}^k \frac{1}{j!} \nabla_{e_i} (u^j T_{k-j}) (e_i), \\
 &= \operatorname{div} T_k + \sum_{i=1}^n \sum_{j=1}^k \frac{1}{j!} \nabla_{e_i} (u^j T_{k-j}) (e_i).
 \end{aligned}$$

And we have

$$\begin{aligned}
 \nabla_{e_i} ((u^j T_{k-j})) (e_i) &= \nabla_{e_i} ((u^j T_{k-j}) e_i) - u^j T_{k-j} (\nabla_{e_i} e_i), \\
 &= \langle \nabla u^j, e_i \rangle T_{k-j} (e_i) + u^j \nabla_{e_i} ((T_{k-j}) e_i) - u^j T_{k-j} (\nabla_{e_i} e_i), \\
 &= ju^{j-1} \langle \nabla u, e_i \rangle T_{k-j} (e_i) + u^j [\nabla_{e_i} (T_{k-j} (e_i)) - T_{k-j} (\nabla_{e_i} e_i)], \\
 &= ju^{j-1} \langle \nabla u, e_i \rangle T_{k-j} (e_i) + u^j [\nabla_{e_i} (T_{k-j} (e_i)) - T_{k-j} (\nabla_{e_i} e_i)], \\
 &= ju^{j-1} \langle \nabla u, e_i \rangle T_{k-j} (e_i) + u^j \nabla_{e_i} (T_{k-j}) (e_i).
 \end{aligned}$$

On the other hand, we have

$$\begin{aligned}
 \sum_{i=1}^n \sum_{j=1}^k \frac{1}{j!} ju^{j-1} \langle \nabla u, e_i \rangle T_{k-j} (e_i) &= \sum_{i=1}^n \langle \nabla u, e_i \rangle \sum_{j=1}^k \frac{u^{j-1}}{(j-1)!} T_{k-j} (e_i), \\
 &= \sum_{i=1}^n \langle \nabla u, e_i \rangle \sum_{l=0}^{k-1} \frac{u^l}{l!} T_{k-l-1} (e_i), \\
 &= \sum_{i=1}^n (T_{k-1}^\infty) (\langle \nabla u, e_i \rangle e_i), \\
 &= T_{k-1}^\infty \circ \nabla u.
 \end{aligned}$$

And

$$\sum_{i=1}^n \sum_{j=1}^k \frac{1}{j!} u^j \nabla_{e_i} (T_{k-j}) (e_i) = \sum_{j=1}^k \frac{u^j}{j!} \operatorname{div} T_{k-j}.$$

Summarize all these relations we obtain the desire formula.

In particular, if \overline{M}^{n+1} has constant sectional curvature, then T_k are divergence-free, $\operatorname{div} T_{k-j} = 0$ (see [4]). The desire relation can be deduced by a recursive argument. \square

3 Main results

In this section we derive some integral formulae on manifolds with density. In order to derive our formulae, we consider the following configuration.

Let $p \in M^n$ and $\{e_1, \dots, e_n\}$ be an orthonormal basis of $T_p M^n$ that diagonalizes A . Then it diagonalizes also T_k^∞ . Denoting by μ_1, \dots, μ_n the eigenvalues of A with respect to the basis $\{e_1, \dots, e_n\}$.

We have

$$\langle \operatorname{div} T_k^\infty, \bar{\nabla}_N N \rangle = \operatorname{div} (T_k^\infty \bar{\nabla}_N N) - \sum_{i=1}^n \langle T_k^\infty (e_i), \bar{\nabla}_{e_i} \bar{\nabla}_N N \rangle.$$

This gives

$$\begin{aligned} \operatorname{div} (T_k^\infty \bar{\nabla}_N N) &= \langle \operatorname{div} T_k^\infty, \bar{\nabla}_N N \rangle + \sum_{i=1}^n \langle T_k^\infty (e_i), \bar{\nabla}_{e_i} \bar{\nabla}_N N \rangle, \\ &= \langle \operatorname{div} T_k^\infty, \bar{\nabla}_N N \rangle + \sum_{i=1}^n \sigma_{k,i}^\infty \langle e_i, \bar{\nabla}_{e_i} \bar{\nabla}_N N \rangle. \end{aligned} \quad (3.1)$$

Where $\sigma_{k,i}^\infty$ is the eigenvalue of T_k^∞ with respect to e_i .

On the other hand

$$-\langle e_i, \bar{\nabla}_{e_i} \bar{\nabla}_N N \rangle = \langle \bar{\nabla}_{e_i} e_i, \bar{\nabla}_N N \rangle + \langle \bar{\nabla}_{e_i} N, \bar{\nabla}_N e_i \rangle + \langle N, \bar{\nabla}_{e_i} \bar{\nabla}_N N \rangle.$$

Using now the Codazzi equation, we have

$$\begin{aligned} \langle e_i, \bar{\nabla}_{e_i} \bar{\nabla}_N N \rangle &= \langle \bar{\nabla}_N (\bar{\nabla}_{e_i} N), e_i \rangle + \langle \bar{\nabla}_{\bar{\nabla}_{e_i} N} N, e_i \rangle - \langle \bar{\nabla}_{\bar{\nabla}_N e_i} N, e_i \rangle - \langle R(e_i, N) e_i, N \rangle, \\ &= N \langle \bar{\nabla}_{e_i} N, e_i \rangle - \langle \bar{\nabla}_{e_i} N, \bar{\nabla}_N e_i \rangle + \langle A^2 e_i, e_i \rangle + \langle A (\bar{\nabla}_{e_i} N), e_i \rangle \\ &\quad - \langle R(e_i, N) e_i, N \rangle, \\ &= -\langle \bar{\nabla} \mu_i, N \rangle + \langle A^2 e_i, e_i \rangle - \langle (\bar{\nabla}_N A) e_i, e_i \rangle + \langle \bar{\nabla}_N (A e_i), e_i \rangle \\ &\quad - \langle R(e_i, N) e_i, N \rangle, \\ &= -\langle \bar{\nabla} \mu_i, N \rangle + \langle A^2 e_i, e_i \rangle - \langle (\bar{\nabla}_N A) e_i, e_i \rangle + \langle \bar{\nabla}_N (\mu_i e_i), e_i \rangle \\ &\quad - \langle R(e_i, N) e_i, N \rangle, \\ &= -\langle \bar{\nabla} \mu_i, N \rangle + \langle A^2 e_i, e_i \rangle - \langle (\bar{\nabla}_N A) e_i, e_i \rangle \\ &\quad + (\mu_i \langle \bar{\nabla}_N e_i, e_i \rangle + \langle (\bar{\nabla}_N \mu_i) e_i, e_i \rangle) - \langle R(e_i, N) e_i, N \rangle, \\ &= -\langle \bar{\nabla} \mu_i, N \rangle + \langle A^2 e_i, e_i \rangle - \langle (\bar{\nabla}_N A) e_i, e_i \rangle + \mu_i \langle \bar{\nabla}_N e_i, e_i \rangle + \langle \bar{\nabla} \mu_i, N \rangle \\ &\quad - \langle R(e_i, N) e_i, N \rangle, \\ &= \langle A^2 e_i, e_i \rangle - \langle (\bar{\nabla}_N A) e_i, e_i \rangle - \langle R(e_i, N) e_i, N \rangle. \end{aligned}$$

On the other hand, we have

$$\begin{aligned} \sum_{i=1}^n \sigma_{k,i}^\infty \langle A^2 e_i, e_i \rangle &= \operatorname{tr} (A^2 T_k^\infty), \\ &= \sigma_{k+1}^\infty \operatorname{tr} A - \operatorname{tr} (A T_{k+1}^\infty), \\ &= \sigma_{k+1}^\infty (\sigma_1^\infty - \langle \bar{\nabla} f, N \rangle) - (k+2) \sigma_{k+2}^\infty + \langle \bar{\nabla} f, N \rangle \sigma_{k+1}^\infty, \\ &= \sigma_1^\infty \sigma_{k+1}^\infty - (k+2) \sigma_{k+2}^\infty, \end{aligned}$$

and [2]

$$\sum_{i=1}^n \sigma_{k,i}^\infty \langle (\bar{\nabla}_N A) e_i, e_i \rangle = \operatorname{tr} (T_k^\infty \circ \bar{\nabla}_N A) = N(\sigma_{k+1}^\infty) - N(\langle \bar{\nabla} f, N \rangle) \sigma_k^\infty.$$

It is not difficult to see that

$$\begin{aligned} \operatorname{div}(\sigma_{k+1}^\infty N) &= N(\sigma_{k+1}^\infty) + \sigma_{k+1}^\infty \cdot \operatorname{div} N, \\ &= N(\sigma_{k+1}^\infty) - \sigma_1^\infty \sigma_{k+1}^\infty + \langle \bar{\nabla} f, N \rangle \sigma_{k+1}^\infty. \end{aligned}$$

Finally

$$\sum_{i=1}^n \sigma_{k,i}^\infty \langle (\bar{\nabla}_N A) e_i, e_i \rangle = \operatorname{div}(\sigma_{k+1}^\infty N) + \sigma_1^\infty \sigma_{k+1}^\infty - \langle \bar{\nabla} f, N \rangle \sigma_{k+1}^\infty - N(\langle \bar{\nabla} f, N \rangle) \sigma_k^\infty.$$

Replacing in (3.6) we get

$$\begin{aligned} \operatorname{div}(T_k^\infty \bar{\nabla}_N N + \sigma_{k+1}^\infty N) &= \langle \operatorname{div} T_k^\infty, \bar{\nabla}_N N \rangle - (k+2) \sigma_{k+2}^\infty + \langle \bar{\nabla} f, N \rangle \sigma_{k+1}^\infty + N(\langle \bar{\nabla} f, N \rangle) \sigma_k^\infty \\ &\quad + \operatorname{tr}(R(N) T_k^\infty). \end{aligned}$$

Integrating the two sides of the above relation and applying the divergence theorem, we obtain

Theorem 3.1. *Let $\psi : M^n \longrightarrow \overline{M}_f^{n+1}$ be a closed oriented hypersurface of a weighted manifold \overline{M}_f^{n+1} . Denoting by N a unit vector field normal to M^n in \overline{M}_f^{n+1} . Then for every $0 \leq k \leq n-2$, we have :*

$$\int_{M^n} [\langle \operatorname{div} T_k^\infty, \bar{\nabla}_N N \rangle - (k+2) \sigma_{k+2}^\infty + \langle \bar{\nabla} f, N \rangle \sigma_{k+1}^\infty + N(\langle \bar{\nabla} f, N \rangle) \sigma_k^\infty + \operatorname{tr}(R(N) T_k^\infty)] dv_f = 0. \quad (3.2)$$

Taking $k = 0$, we have

Lemma 3.2. *Under the hypothesis of the above theorem, we have*

$$\int_{M^n} 2\sigma_2^\infty dv_f = \int_{M^n} \langle \bar{\nabla} f, N \rangle \sigma_1^\infty dv_f + \int_{M^n} \langle \bar{\nabla} f, \nabla_N N \rangle dv_f + \int_{M^n} \operatorname{Ric}_f(N, N) dv_f. \quad (3.3)$$

Where Ric_f is the Bakry-Émery-Ricci tensor define in []equation* $\operatorname{Ric}_f = \operatorname{Ric} + \operatorname{Hess} f$.

In particular if \overline{M}^{n+1} is non weighted, then (3.3) reduced to the well known formula

$$\int_{M^n} 2\sigma_2 dv = \int_M \operatorname{Ric}(N, N) dv.$$

Let consider the case where \overline{M}^{n+1} is a non weighted Riemannian manifold, then we have

Theorem 3.3. *Let $\psi : M^n \longrightarrow \overline{M}^{n+1}$ be a closed oriented hypersurface of \overline{M}^{n+1} . Denoting by N a unit vector field normal to M^n in \overline{M}^{n+1} . Then for every $0 \leq k \leq n-2$, we have :*

$$\int_{M^n} [\langle \operatorname{div} T_k, \bar{\nabla}_N N \rangle - (k+2) \sigma_{k+2} + \operatorname{tr}(R(N) T_k)] dv = 0 \quad (3.4)$$

In this case if \overline{M}^{n+1} has constant sectional curvature c , then T_k are divergence-free and

$$\operatorname{tr}(R(N) T_k) = c \cdot (n-k) \sigma_k.$$

Hence

$$(k+2) \int_{M^n} \sigma_{k+2} dv = c \cdot (n-k) \int_{M^n} \sigma_k dv.$$

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