# Stability, Boundedness and Square Integrability Of Solutions To Certain Third Order Neutral Delay Differential Equations 

Anes MOULAI-KHATIR, Moussadek REMILI and Djamila BELDJERD<br>Communicated by Jamil Tunc

MSC 2010 Classifications: Primary 34D20, Secondary 34D40.
Keywords and phrases: Asymptotic Stability, Boundedness, Lyapunov functional, Neutral Differential Equation of Third Order.


#### Abstract

By constructing a Lyapunov functional, we obtain some sufficient conditions which guarantee the stability, boundedness and square integrability of solutions for some nonlinear neutral delay differential equations of third order. Our results improve and extend some well known results in the literature and one example is given for illustration of the subject.


## 1 Introduction

In this paper we consider a specific class of third order neutral delay differential equations of the following form

$$
\begin{equation*}
\left(x^{\prime \prime}(t)+\beta(t) x^{\prime \prime}(t-r)\right)^{\prime}+\Psi\left(x^{\prime}(t)\right) x^{\prime \prime}(t)+g\left(x^{\prime}(t)\right)+f(x(t-\sigma))=0, \tag{1.1}
\end{equation*}
$$

and

$$
\begin{align*}
\left(x^{\prime \prime}(t)+\beta(t) x^{\prime \prime}(t-r)\right)^{\prime} & +\Psi\left(x^{\prime}(t)\right) x^{\prime \prime}(t)+g\left(x^{\prime}(t)\right) \\
& +f(x(t-\sigma))=p\left(t, x, x(t-r), x^{\prime}(t), x^{\prime}(t-r), x^{\prime \prime}\right), \tag{1.2}
\end{align*}
$$

for all $t \geq T \geq t_{0}+\rho$, where $\rho=\sup \{r, \sigma\}$, and the functions $\left.\Psi\left(x^{\prime}(t)\right), g\left(x^{\prime}(t-r)\right)\right), f(x), \beta(t)$ and $p\left(t, x(t), x(t-r), x^{\prime}(t), x^{\prime}(t-r), x^{\prime \prime}(t)\right)$ are continuous in their respective arguments. Besides, it is supposed that the derivatives $f^{\prime}(x), g^{\prime}(y), \beta^{\prime}(t)$ are continuous for all $x, y$ with $f(0)=g(0)=$ $0,0 \leq \beta(t)$ and $\alpha \leq \beta^{\prime}(t) \leq 0$.

Neutral differential equations have many applications. For example, these equations arise in the study of two or more simple oscillatory systems with some interconnections between them and in modeling physical problems such as vibration of masses attached to an elastic bar. See [18] for reviews of this theory. In the qualitative analysis of such systems, the stability and asymptotic behavior of solutions play an important role. There is the permanent interest in obtaining new sufficient conditions for the stability and boundedness of the solutions of third order neutral differential equations. In many references the authors dealt with the problems by considering Lyapunov functions or functionals and obtained the criteria for the stability and boundedness see $[1,2,8,10,11,12,13,14,15,16,17,20,21]$.

By a solution of (1.1) (respectively (1.2)) we mean a continuous function $x:\left[t_{x}, \infty\right) \rightarrow \mathbb{R}$ such that $Z(t)=x^{\prime \prime}(t)+\beta(t) x^{\prime \prime}(t-r) \in C^{1}\left(\left[t_{x}, \infty\right), \mathbb{R}\right)$ and which satisfies equation (1.1) (resp. eq. (1.2)) on $\left[t_{x}, \infty\right)$. Without further mention, we will assume throughout that every solution $x(t)$ of (1.1) (eq. (1.2)) under consideration here is continuable to the right and nontrivial, i.e $x(t)$ is defined on some ray $\left[t_{x}, \infty\right)$. Moreover, we tacitly assume that (1.1) (eq. (1.2)) possesses such solutions.

## 2 Stability

Suppose that there are positive constants $d_{0}, d_{1}, d, M, \delta, \Psi_{0}, \Psi_{1}$ and $\eta$ such that the following conditions which will be used on the functions that appeared in equation (1.1) are satisfied:
i) $\Psi_{0}<\Psi(y)<\Psi_{1}$.
ii) $\frac{f(x)}{x} \geq M>0(x \neq 0)$, and $\left|f^{\prime}(x)\right| \leq \delta$ for all $x$.
iii) $d^{2}<d_{0} \leq \frac{g(y)}{y} \leq d_{1}$.
iv) $\frac{\delta}{2}<d<\Psi_{0}$.
v) $\int_{T}^{t}\left|\beta^{\prime}(s)\right| d s<\eta$.

Remark 2.1. It's evident to see that $\beta(t) \leq \beta(T)=c$, for all $t \geq T$.
For the sake of simplicity, we introduce the following notation

$$
Y(t)=x^{\prime}(t)+\beta(t) x^{\prime}(t-r)
$$

Let us, for convenience, replace (1.1) by the equivalent differential system

$$
\left\{\begin{array}{l}
x^{\prime}=y  \tag{2.1}\\
y^{\prime}=z \\
Z^{\prime}=-\Psi(y) z-g(y)-f(x)+\int_{t-\sigma}^{t} f^{\prime}(x(s)) y(s) d s
\end{array}\right.
$$

It's easy to see from (2.1) that

$$
\begin{aligned}
Y(t) & =y(t)+\beta(t) y(t-r) \\
Z(t) & =z(t)+\beta(t) z(t-r) \\
Y^{\prime}(t) & =Z(t)+\beta^{\prime}(t) y(t-r)
\end{aligned}
$$

For the case $p\left(t, x(t), x(t-r), x^{\prime}(t), x^{\prime}(t-r), x^{\prime \prime}(t)\right) \equiv 0$, the stability result of this paper is the following theorem.
Theorem 2.2. If in addition to the hypotheses (i)-(v), suppose there exists a positive constant $\varepsilon$ such that the following is also satisfied

$$
\sigma<\frac{2}{\delta} \min \left\{\frac{\varepsilon}{c}, \frac{A_{1}}{1+c+2 d}, A_{2}\right\}
$$

where

$$
\begin{align*}
-A_{1} & =-d d_{0}+\delta+c\left(\frac{d_{1}^{2}}{2}+\delta\right)+(1+c)^{2}+\frac{3 \alpha}{2}<0 \\
-A_{2} & =-B_{0}+(1+c)^{2}+\frac{c}{2}\left(1+2 B_{1}\right)+\varepsilon<0  \tag{2.2}\\
B_{0} & =\Psi_{0}-d, \text { and } B_{1}=\Psi_{1}-d
\end{align*}
$$

Then the null solution of (2.1) is asymptotically stable.
Proof. The proof of this theorem depends on properties of the continuously differentiable function $W=W\left(t, x_{t}, y_{t}, z_{t}\right)$ defined as

$$
\begin{equation*}
W(t)=V e^{-\frac{1}{\omega} \int_{T}^{t}\left|\beta^{\prime}(s)\right| d s} \tag{2.3}
\end{equation*}
$$

where

$$
\begin{align*}
V= & V_{1}+V_{2}+\lambda \int_{-\sigma}^{0} \int_{t+s}^{t} y^{2}(\xi) d \xi d s \\
V_{1}= & d F(x)+f(x) Y+Y^{2}  \tag{2.4}\\
V_{2}= & \frac{1}{2} Z^{2}+d y Z+\int_{0}^{y}(g(u)+d \Psi(u) u) d u  \tag{2.5}\\
& +\int_{t-r}^{t}\left(\mu_{1} y^{2}(s)+\mu_{2} z^{2}(s)\right) d s \tag{2.6}
\end{align*}
$$

and

$$
F(x)=\int_{0}^{x} f(u) d u
$$

$\lambda, \mu_{1}$ and $\mu_{2}$ are positives constants which will be specified later in the proof.
Noting that

$$
2 \int_{0}^{x} f^{\prime}(u) f(u) d u=f^{2}(x)
$$

and using (iv), we have

$$
\begin{aligned}
V_{1} & =d \int_{0}^{x} f(u) d u+\left(Y+\frac{1}{2} f(x)\right)^{2}-\frac{1}{4} f^{2}(x) \\
& \geq d \int_{0}^{x} f(u) d u-\frac{1}{2} \int_{0}^{x} f^{\prime}(u) f(u) d u \\
& \geq \int_{0}^{x}\left(d-\frac{\delta}{2}\right) f(u) d u \\
& \geq\left(d-\frac{\delta}{2}\right) F(x)
\end{aligned}
$$

An application of condition (ii), give

$$
F(x)=\int_{0}^{x} f(u) d u \geq \frac{1}{2} M x^{2}
$$

From conditions (i) and (iii), we have

$$
\int_{0}^{y}(g(u)+d \Psi(u) u) d u \geq \frac{1}{2}\left(d_{0}+d \Psi_{0}\right) y^{2}
$$

Furthermore,

$$
\begin{aligned}
\frac{1}{2} Z^{2}+d y Z+\frac{d_{0}}{2} y^{2}= & \frac{1}{4}(d y+Z)^{2}+\frac{d_{0}}{4}\left(y+\frac{d}{d_{0}} Z\right)^{2} \\
& +\frac{1}{4}\left(d_{0}-d^{2}\right) y^{2}+\frac{1}{4}\left(1-\frac{d^{2}}{d_{0}}\right) Z^{2}
\end{aligned}
$$

Since $\int_{t-r}^{t}\left(\mu_{1} y^{2}(s)+\mu_{2} z^{2}(s)\right) d s \geq 0$, we obtain

$$
V_{2} \geq k_{0}\left(y^{2}+Z^{2}\right)
$$

where

$$
k_{0}=\min \left\{\frac{d \Psi_{0}}{2}+\frac{1}{4}\left(d_{0}-d^{2}\right), \frac{1}{4}\left(1-\frac{d^{2}}{d_{0}}\right)\right\}
$$

Thus,

$$
\begin{equation*}
V \geq K_{0}\left(x^{2}+y^{2}+Z^{2}\right) \tag{2.7}
\end{equation*}
$$

where

$$
K_{0}=\min \left\{\frac{1}{2} M\left(d-\frac{\delta}{2}\right), k_{0}\right\} .
$$

From (2.3), (2.7) and condition (v) we have

$$
\begin{equation*}
W \geq K_{1}\left(x^{2}+y^{2}+Z^{2}\right) \tag{2.8}
\end{equation*}
$$

with

$$
K_{1}=K_{0} e^{-\frac{\eta}{\omega}}
$$

The time derivative of V gives

$$
V^{\prime}=U_{1}+U_{2}+U_{3}
$$

where

$$
\begin{aligned}
U_{1}= & {\left[d-\Psi(y)+\mu_{2}\right] z^{2}+\left[f^{\prime}(x)+\mu_{1}+\lambda \sigma\right] y^{2}-d g(y) y } \\
& +\left[-\mu_{1}+2 \beta^{\prime}(t) \beta(t)\right] y^{2}(t-r)-\mu_{2} z^{2}(t-r) \\
U_{2}= & \left(\beta(t) f^{\prime}(x)+2 \beta^{\prime}(t)\right) y y(t-r)+\beta^{\prime}(t) f(x) y(t-r) \\
& +\beta(t)(d-\Psi(y)) z(t-r) z+2 y z \\
& +2 \beta(t) y z(t-r)+2 \beta(t) y(t-r) z+2 \beta^{2}(t) y(t-r) z(t-r) \\
& -\beta(t) z(t-r) g(y)
\end{aligned}
$$

and

$$
U_{3}=[Z+d y] \int_{t-\sigma}^{t} f^{\prime}\left(x(s) y(s) d s-\lambda \int_{t-\sigma}^{t} y^{2}(s) d s\right.
$$

By conditions (i)-(iii) and the fact that $\beta(t) \leq c$ and $|f(x)|<\delta|x|$, we get

$$
\begin{aligned}
U_{1} \leq & {\left[-B_{0}+\mu_{2}\right] z^{2}+\left[-d d_{0}+\delta+\mu_{1}+\lambda \sigma\right] y^{2} } \\
& +\left[-\mu_{1}+2 \beta^{\prime}(t) \beta(t)\right] y^{2}(t-r)-\mu_{2} z^{2}(t-r)
\end{aligned}
$$

Also by using Schwartz inequality we get

$$
\begin{aligned}
U_{2} \leq & \frac{\left|\beta^{\prime}(t)\right| \delta^{2}}{2} x^{2}+\left(1+\frac{c}{2}\left(2+d_{1}^{2}+\delta\right)+\left|\beta^{\prime}(t)\right|\right) y^{2} \\
& +\left(1+\frac{c}{2}\left(2+B_{1}\right)\right) z^{2} \\
& +\left(c\left(1+c+\frac{\delta}{2}\right)+\frac{3 \alpha}{2}\right) y^{2}(t-r) \\
& +\left(\frac{c}{2}\left(B_{1}+2 c+3\right)\right) z^{2}(t-r)
\end{aligned}
$$

and

$$
\begin{aligned}
U_{3} \leq & \frac{d \delta \sigma}{2} y^{2}+\frac{\delta \sigma}{2} z^{2}+\frac{c \delta \sigma}{2} z^{2}(t-r) \\
& +\left[\frac{\delta}{2}(1+c+d)-\lambda\right] \int_{t-\sigma}^{t} y^{2}(s) d s
\end{aligned}
$$

So, after rearrangement and using the fact that $\alpha \leq \beta^{\prime}(t) \leq 0$, we have

$$
\begin{aligned}
V^{\prime} \leq & {\left[-d d_{0}+\delta+1+\frac{c}{2}\left(2+d_{1}^{2}+\delta\right)+\mu_{1}+\left(\frac{d \delta}{2}+\lambda\right) \sigma\right] y^{2} } \\
& +\left[-B_{0}+1+\frac{c}{2}\left(2+B_{1}\right)+\mu_{2}+\frac{\delta \sigma}{2}\right] z^{2} \\
& +\left[-\mu_{1}+c\left(1+c+\frac{\delta}{2}\right)+\frac{3 \alpha}{2}\right] y^{2}(t-r) \\
& +\left[-\mu_{2}+\frac{c}{2}\left(3+B_{1}+2 c\right)+\frac{c \delta \sigma}{2}\right] z^{2}(t-r) \\
& +\left[\frac{\delta^{2}}{2} x^{2}+y^{2}\right]\left|\beta^{\prime}(t)\right| \\
& +\left[\frac{\delta}{2}(1+c+d)-\lambda\right] \int_{t-\sigma}^{t} y^{2}(s) d s
\end{aligned}
$$

By taking

$$
\begin{aligned}
\frac{\delta}{2}(1+c+d) & =\lambda \\
c\left(1+c+\frac{\delta}{2}\right)+\frac{3 \alpha}{2} & =\mu_{1} \\
\frac{c}{2}\left(3+B_{1}+2 c\right)+\varepsilon & =\mu_{2}
\end{aligned}
$$

we get

$$
\begin{aligned}
V^{\prime} \leq & {\left[-d d_{0}+\delta+c\left(\frac{d_{1}^{2}}{2}+\delta\right)+(1+c)^{2}+\frac{3 \alpha}{2}+\delta(1+c+2 d) \frac{\sigma}{2}\right] y^{2} } \\
& +\left[-B_{0}+(1+c)^{2}+\frac{c}{2}\left(1+2 B_{1}\right)+\varepsilon+\delta \frac{\sigma}{2}\right] z^{2} \\
& +\left[-\varepsilon+\frac{c \delta \sigma}{2}\right] z^{2}(t-r) \\
& +\left[\frac{\delta^{2}}{2} x^{2}+y^{2}\right]\left|\beta^{\prime}(t)\right| .
\end{aligned}
$$

With the use of (2.2), we obtain

$$
\begin{aligned}
V^{\prime} \leq & {\left[-A_{1}+[\delta(1+c+2 d)] \frac{\sigma}{2}\right] y^{2}(t)+\left[-A_{2}+\delta \frac{\sigma}{2}\right] z^{2}(t) } \\
& +\left[-\varepsilon+\frac{c \delta \sigma}{2}\right] z^{2}(t-r) \\
& +\left|\beta^{\prime}(t)\right|\left[\frac{\delta^{2}}{2} x^{2}(t)+y^{2}(t)\right]
\end{aligned}
$$

If

$$
\sigma<\frac{2}{\delta} \min \left\{\frac{\varepsilon}{c}, \frac{A_{1}}{1+c+2 d}, A_{2}\right\}
$$

then

$$
V^{\prime} \leq-K_{2}\left(y^{2}(t)+z^{2}(t)\right)+\left|\beta^{\prime}(t)\right|\left[\frac{\delta^{2}}{2} x^{2}(t)+y^{2}(t)\right]
$$

where

$$
K_{2}=\min \left\{-A_{1}+[\delta(1+c+2 d)] \frac{\sigma}{2},-A_{2}+\delta \frac{\sigma}{2}\right\}
$$

From condition (v), one can see that

$$
e^{\left(-\frac{\eta}{\omega}\right)}<e^{\left(-\frac{1}{\omega} \int_{T}^{t}\left|\beta^{\prime}(s)\right| d s\right)}=E(t)<1
$$

Hence, by (2.3), we have

$$
\begin{align*}
W^{\prime}(t) & =\left(V^{\prime}-\frac{\left|\beta^{\prime}(t)\right|}{\omega} V\right) E(t) \\
& \leq\left(-K_{2}\left[y^{2}(t)+z^{2}(t)\right]+\left|\beta^{\prime}(t)\right|\left[\frac{\delta^{2}}{2} x^{2}(t)+y^{2}(t)\right]-\frac{K_{0}\left|\beta^{\prime}(t)\right|}{\omega}\left(x^{2}+y^{2}+Z^{2}\right)\right) E(t) \\
& \leq\left(-K_{2}\left[y^{2}(t)+z^{2}(t)\right]+K_{3}\left|\beta^{\prime}(t)\right|\left(x^{2}+y^{2}+Z^{2}\right)-\frac{K_{0}\left|\beta^{\prime}(t)\right|}{\omega}\left(x^{2}+y^{2}+Z^{2}\right)\right) E(t) \\
& \leq-K_{4}\left[y^{2}(t)+z^{2}(t)\right] \tag{2.9}
\end{align*}
$$

where

$$
K_{4}=K_{2} e^{-\frac{\eta}{\omega}}, K_{3}=\frac{1}{2} \max \left\{2, \delta^{2}\right\}, \omega=\frac{K_{0}}{K_{3}} .
$$

From (2.9), $W_{3}(\|X\|)=K_{2} e^{-\frac{\eta}{\omega}}\left[y^{2}(t)+z^{2}(t)\right]$ is a positive definite function. The above discussion guarantees that the null solution of (2.1) is asymptotically stable and completes the proof of Theorem 2.2.

## 3 Boundedness

For the case $p(t, x, y, x(t-r), y(t-r), z(t))=p(\cdot) \neq 0$, equation (1.1) is equivalent to the system

$$
\left\{\begin{array}{l}
x^{\prime}=y  \tag{3.1}\\
y^{\prime}=z \\
Z^{\prime}=-\Psi(y) z-g(y)-f(x)+p(\cdot)+\int_{t-\sigma}^{t} f^{\prime}(x(s)) y(s) d s
\end{array}\right.
$$

Theorem 3.1. Assume that all the conditions of Theorem 2.2 are satisfied and there exist positive constants $q_{1}$ and $q_{2}$ such that
$\left.I_{1}\right)|p(t, x, y, x(t-r), y(t-r), z(t))| \leq q(t)<q_{1}$,
$\left.I_{2}\right)\left|\int_{0}^{t} q(s) d s\right|<q_{2}$.
Then there exists a positive constant $D$ such that any solution of (3.1) satisfies

$$
\begin{equation*}
|x(t)| \leq D,|y(t)| \leq D,|Z(t)| \leq D \tag{3.2}
\end{equation*}
$$

Proof. On differentiating (2.3) along the system (3.1), we obtain

$$
\begin{aligned}
W_{(3.1)}^{\prime} & =W_{(2.1)}^{\prime}+(Z p(\cdot)+d y p(\cdot)) e^{-\frac{1}{\omega} \int_{T}^{t}\left|\beta^{\prime}(s)\right| d s} \\
& \leq Z p(\cdot)+\operatorname{dyp}(\cdot)
\end{aligned}
$$

Using condition $\left(I_{1}\right)$, we get

$$
W_{(3.1)}^{\prime} \leq q(t)|Z|+d q(t)|y|
$$

Now, the inequality $|u| \leq u^{2}+1$ lead

$$
\begin{align*}
W_{(3.1)}^{\prime} & \leq K_{5} q(t)\left[y^{2}+Z^{2}+2\right] \\
& \leq K_{5} q(t)\left[x^{2}+y^{2}+Z^{2}+2\right] \tag{3.3}
\end{align*}
$$

where $K_{5}=\max \{1, d\}$.
In view of (2.8), the above estimates imply that

$$
\begin{equation*}
W_{(3.1)}^{\prime} \leq \frac{K_{5}}{K_{1}} q(t) W+K_{6} q(t) \tag{3.4}
\end{equation*}
$$

with $K_{6}=2 K_{5}$. Integrating both sides from $t_{1}$ to $t$, we easily obtain

$$
W(t)-W(T) \leq K_{6} \int_{T}^{t} q(s) d s+\frac{K_{5}}{K_{1}} \int_{T}^{t} W(s) q(s) d s
$$

Let

$$
\begin{equation*}
q_{3}=W(T)+K_{6} q_{2} \tag{3.5}
\end{equation*}
$$

Thus

$$
W(t) \leq q_{3}+\frac{K_{5}}{K_{1}} \int_{T}^{t} W(s) q(s) d s
$$

By using Gronwall inequality, it follows that

$$
\begin{equation*}
W(t) \leq q_{3} \exp \left(\frac{K_{5}}{K_{1}} \int_{T}^{t} q(s) d s\right) \leq q_{4} \tag{3.6}
\end{equation*}
$$

where $q_{4}=q_{3} \exp \left(\frac{K_{5}}{K_{1}} q_{2}\right)$. This result implies that there exists a constant $D$ such that

$$
|x(t)| \leq D,|y(t)| \leq D,|Z(t)| \leq D
$$

This completes the proof of Theorem 3.1.

## 4 Square Integrability

Our next result concerns the square integrability of solutions to equation (1.2).
Theorem 4.1. If conditions (i)-(v), ( $I_{1}$ ) and ( $I_{2}$ ) hold, then any solution $x$ of (1.2) satisfies

$$
\int_{t_{0}}^{\infty}\left(x^{\prime \prime 2}(s)+x^{\prime 2}(s)+x^{2}(s)\right) d s<\infty
$$

Proof. Define $H(t)$ as

$$
\begin{equation*}
H(t)=W(t)+\varepsilon_{0} \int_{T}^{t}\left(z^{2}(s)+y^{2}(s)\right) d s \tag{4.1}
\end{equation*}
$$

where $\varepsilon_{0}>0$, is a constant to be specified later. By differentiating $H(t)$ and using (3.4), we obtain

$$
H^{\prime}(t) \leq\left[\varepsilon_{0}-K_{4}\right]\left(z^{2}(t)+y^{2}(t)\right)+\frac{K_{5}}{K_{1}} q(t) W+K_{6} q(t)
$$

If we Choose $\varepsilon_{0}-K_{4}<0$, then from (3.6) we get

$$
\begin{equation*}
H^{\prime}(t) \leq K_{7} q(t) \tag{4.2}
\end{equation*}
$$

where $K_{7}=\frac{K_{5}}{K_{1}} q_{4}+K_{6}$. Integrating (4.2) from $T$ to $t$, and using condition $\left(I_{2}\right)$ of Theorem 3.1, we obtain

$$
H(t)-H(T)=\int_{T}^{t} H^{\prime}(s) d s \leq K_{7} q_{2}
$$

Using (3.5) and equality $H(T)=W(T)$, we get

$$
H(t) \leq \frac{K_{5}}{K_{1}} q_{4} q_{2}+q_{3}
$$

We can conclude by (4.1) that

$$
\int_{T}^{t}\left(z^{2}(s)+y^{2}(s)\right) d s<\frac{K_{5} q_{4} q_{2}+K_{1} q_{3}}{K_{1} \varepsilon_{0}}
$$

which imply the existence of positive constants $\sigma_{1}$ and $\sigma_{2}$, such that

$$
\int_{T}^{t} y^{2}(s) d s \leq \sigma_{1} \text { and } \int_{T}^{t} z^{2}(s) d s \leq \sigma_{2}
$$

Hence

$$
\begin{equation*}
\int_{T}^{t} x^{\prime 2}(s) d s \leq \sigma_{1} \text { and } \int_{T}^{t} x^{\prime \prime 2}(s) d s \leq \sigma_{2} \tag{4.3}
\end{equation*}
$$

Next multiplying (1.2) by $x(t-\sigma)$, we obtain

$$
\begin{align*}
& {\left[x^{\prime \prime}(t)+\beta x^{\prime \prime}(t-r)\right]^{\prime} x(t-\sigma)+\Psi\left(x^{\prime}(t)\right) x^{\prime \prime}(t) x(t-\sigma)+g\left(x^{\prime}(t)\right) x(t-\sigma)} \\
& +f(x(t-\sigma)) x(t-\sigma)=p\left(t, x, x(t-\sigma), x^{\prime}(t), x^{\prime}(t-\sigma), x^{\prime \prime}\right) x(t-\sigma) \tag{4.4}
\end{align*}
$$

Integrating (4.4) from $T$ to $t$, we have

$$
\begin{equation*}
\int_{T}^{t} f(x(s-\sigma)) x(s-\sigma) d s=L_{1}(t)+L_{2}(t)+L_{3}(t)+L_{4}(t) \tag{4.5}
\end{equation*}
$$

where

$$
\begin{aligned}
L_{1}(t) & =-\int_{T}^{t}\left(x^{\prime \prime}(s)+\beta(s) x^{\prime \prime}(s-r)\right) x(s-\sigma) d s \\
L_{2}(t) & =-\int_{T}^{t} \Psi\left(x^{\prime}(s)\right) x^{\prime \prime}(s) x(s-r) d s \\
L_{3}(t) & =-\int_{T}^{t} g\left(x^{\prime}(s)\right) x(s-r) d s \\
L_{4}(t) & =\int_{T}^{t} p\left(t, x, x(s-r), x^{\prime}(t), x^{\prime}(s-r), x^{\prime \prime}\right) x(s-r) d s
\end{aligned}
$$

Integrating by parts and using (3.2) and (4.3), we obtain

$$
\begin{aligned}
L_{1}(t) & =-x(t-\sigma)\left[x^{\prime \prime}(t)+\beta(t) x^{\prime \prime}(t-r)\right]+\int_{T}^{t}\left(\left[x^{\prime \prime}(t)+\beta(s) x^{\prime \prime}(t-r)\right] x^{\prime}(s-\sigma)\right) d s+C_{1} \\
& \leq C_{1}+D^{2}(1+c)+\frac{1}{2} \int_{T}^{t}\left(\left[x^{\prime \prime}(s)+\beta(s) x^{\prime \prime}(s-r)\right]^{2}+x^{\prime 2}(s-\sigma)\right) d s \\
& \leq C_{1}+D^{2}(1+c)+\frac{1}{2} \int_{T}^{t}\left(x^{\prime \prime 2}(s)+c^{2} x^{\prime \prime 2}(s-r)+2 c x^{\prime \prime}(s) x^{\prime \prime}(s-r)+x^{\prime 2}(s-\sigma)\right) d s \\
& \leq l_{1}
\end{aligned}
$$

where

$$
C_{1}=\left|x(T-\sigma)\left[x^{\prime \prime}(T)+\beta(T) x^{\prime \prime}(T-r)\right]\right|
$$

and

$$
l_{1}=C_{1}+D^{2}(1+c)+\frac{1}{2}\left[\left(1+2 c+c^{2}\right) \sigma_{2}+\sigma_{1}\right]
$$

In the same way, after using (i)-(iii), $\left(\mathrm{I}_{1}\right),\left(\mathrm{I}_{2}\right),(3.2)$ and (4.3), one arrives at

$$
\begin{aligned}
L_{2}(t) & \leq \int_{T}^{t}\left|\Psi\left(x^{\prime}(s)\right) x^{\prime \prime}(s) x(s-\sigma)\right| d s \\
& \leq\left(\int_{T}^{t}\left[\Psi\left(x^{\prime}(s)\right) x^{\prime \prime}(s)\right]^{2} d s\right)^{\frac{1}{2}}\left(\int_{T}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}} \\
& \leq l_{2}\left(\int_{T}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}}, \\
L_{3}(t) & \leq \int_{T}^{t}\left|g^{\prime}\left(x^{\prime}(s)\right) x(s-\sigma)\right| d s \\
& \leq\left(\int_{T}^{t}\left[g^{\prime}\left(x^{\prime}(s)\right)\right]^{2} d s\right)^{\frac{1}{2}}\left(\int_{T}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}} \\
& \leq\left(d_{1}^{2} \int_{T}^{t} x^{\prime 2}(s) d s\right)^{\frac{1}{2}}\left(\int_{T}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}} \\
& \leq l_{3}\left(\int_{t_{1}}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}}, \\
L_{4}(t) & \leq \int_{T}^{t}\left|p\left(s, x, y, x(s-\sigma), x^{\prime}(s-\sigma), x^{\prime \prime}(s)\right) x(s-\sigma)\right| d s \\
& \leq D \int_{T}^{t}|q(s)| d s \leq l_{4},
\end{aligned}
$$

where

$$
l_{2}=\sqrt{\Psi_{1}^{2} \sigma_{2}}, l_{3}=\sqrt{d_{1}^{2} \sigma_{1}}, \text { and } l_{4}=D q_{2}
$$

In the other hand from condition (ii), we have

$$
\int_{T}^{t} x(s-\sigma) f(x(s-\sigma)) d s \geq M \int_{T}^{t} x^{2}(s-\sigma) d s
$$

Hence, by (4.5) and condition $I_{3}$ of Theorem 4.1, we obtain

$$
\begin{equation*}
M \int_{T}^{t} x^{2}(s-\sigma) d s \leq l_{1}+l_{2}\left(\int_{T}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}}+l_{3}\left(\int_{T}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}}+l_{4} \tag{4.6}
\end{equation*}
$$

If

$$
\int_{T}^{t} x^{2}(s-\sigma) d s \rightarrow \infty \text { as } t \rightarrow \infty
$$

then dividing both sides of (4.6) by $\left(\int_{T}^{t} x^{2}(s-\sigma) d s\right)^{\frac{1}{2}}$, we immediately obtain a contradiction.
Hence, we deduce that $\int_{T}^{t} x^{2}(s-\sigma) d s<\infty$, then $\int_{T}^{+\infty} x^{2}(s) d s<\infty$. This fact completes the proof of Theorem 4.1.

## 5 Example

As a particular case of (1.2), consider the following third order neutral differential equation

$$
\begin{aligned}
\left(x^{\prime \prime}(t)+\frac{1}{10} e^{-\frac{10}{3} t} x^{\prime \prime}(t-r)\right)^{\prime} & +\left(\frac{11}{2}+\frac{1}{2} \sin x^{\prime}(t)\right) x^{\prime \prime}(t)+(4.775) x^{\prime}(t)+\frac{1}{200} x^{\prime}(t) \cos \left(x^{\prime}(t)\right) \\
& +\left[\frac{19}{10} x(t-r)+\frac{x(t-r)}{\sqrt{10}+|x(t-r)|}\right]=\frac{1}{1+t^{2}+|x|+|y|+|z|}
\end{aligned}
$$

The appearing functions in the equation are as follows

$$
\begin{gathered}
5=\Psi_{0} \leq \Psi(y)=\frac{11}{2}+\frac{1}{2} \sin y \leq \Psi_{1}=6 \\
4.41=d^{2}<d_{0}=4.77 \leq \frac{g(y)}{y}=4.775+\frac{1}{200} \cos y \leq d_{1}=4.87 \\
0<\beta(t)=\frac{1}{10} e^{-\frac{10}{3} t} \leq \frac{1}{10}=c \\
\beta^{\prime}(t)=-\frac{1}{3} e^{-\frac{10}{3} t}<0 \text { and }\left|\beta^{\prime}(t)\right|=\left|-\frac{1}{3} e^{-\frac{10}{3} t}\right| \leq \frac{1}{3}=\alpha \\
1=\frac{\delta}{2}<d=2.1<\Psi_{0}=5
\end{gathered}
$$

and the function

$$
f(x)=\frac{19}{10} x+\frac{x}{\sqrt{10}+|x|}
$$

It is clear, from this relation, that $f(0)=0$. Also, since $0 \leq \frac{1}{\sqrt{10}+|x|} \leq 1$ for all $x$, we have that

$$
\frac{f(x)}{x} \geq \frac{19}{10}=M
$$

for all $x \neq 0$. Moreover

$$
\left|f^{\prime}(x)\right|=\left|\frac{19}{10}+\frac{1}{(\sqrt{10}+|x|)^{2}}\right| \leq 2=\delta
$$

We also have

$$
\begin{aligned}
-d d_{0}+\delta+c\left(\frac{d_{1}^{2}}{2}+\delta\right)+(1+c)^{2}+\frac{3 \alpha}{2} & =-4.91=-A_{1}<0 \\
-B_{0}+(1+c)^{2}+\frac{c}{2}\left(3+2 B_{1}\right)+\varepsilon & =-1.05=-A_{2}<0, \text { for } \varepsilon=\frac{1}{10}
\end{aligned}
$$

The function

$$
p(t, x, y, z)=\frac{1}{1+t^{2}+|x|+|y|+|z|} \leq \frac{1}{1+t^{2}}=q(t)
$$

and

$$
\int_{0}^{+\infty}|q(t)| d t<\infty
$$

for all $t, x, y, z$.
All assumptions of Theorem (4.1) hold true, thus, the conclusions also follow.

## Acknowledgment

The authors would like to thank the reviewers for all of their careful comments and suggestions in relation to this work.

## References

[1] A.T. Ademola, and P.O. Arawomo, Uniform stability and boundedness of solutions of nonlinear delay differential equations of third order. Math. J. Okayama Univ. 55(2013), 157-166.
[2] A.T. Ademola, and P.O Arawomo, O. M. Ogunlaran and E.A. Oyekan. Uniform stability, boundedness and asymptotic behaviour of solutions of some third order nonlinear delay differential equations. Differential Equations and Control Processes, N4 (2013), 43-66.
[3] B. Baculkova, J. Dzurina. On the asymptotic behavior of a class of third order nonlinear neutral differential equations, Cent. Eur. J. Math., 8(2010), 10-91.
[4] Bozena Mihalikova and Eva Kostikova. Boundedness And Oscillation Of Third Order Neutral Differential Equations. Tatra Mt. Math. Publ. 43 (2009), 137-144.
[5] Z. Dosla, P. Liska. Oscillation of third-order nonlinear neutral differential equations. Appl. Math. Lett., 56 (2016), 42-48.
[6] Z. Dosla, P. Liska. Comparison Theorems For Third-Order Neutral Differential Equations. Electronic Journal of Differential Equations, Vol. 2016 (2016), No. 38, pp. 1-13.
[7] L.E. El'sgol'ts, Introduction to the theory of differential equations with deviating arguments. Translated from the Russian by Robert J. McLaughlin Holden-Day, Inc., San Francisco, Calif.-London-Amsterdam (1966).
[8] J.R. Graef, D.Beldjerd and M. Remili. On stability, ultimate boundedness, and existence of periodic solutions of certain third order differential equations with delay. PanAmerican Mathematical Journal 25 (2015), 82-94.
[9] Kulenovic, M. R. S., Ladas, G. Meimaridou, A. Stability of solutions of linear delay differential equations. Proc. Amer. Math. Soc., 100(1987), 433-441.
[10] M.O. Omeike, New results on the stability of solution of some non-autonomous delay differential equations of the third order. Differential Equations and Control Processes 2010 1, (2010), 18-29.
[11] M.O. Omeike, New results on the asymptotic behavior of a third-order nonlinear differential equation. Differential Equations and Applications, Volume 2, Number 1 (2010), 39-51.
[12] M. Remili, and D. Beldjerd, On the asymptotic behavior of the solutions of third order delay differential equations. Rend. Circ. Mat. Palermo, Vol 63, No 3 (2014), 447-455.
[13] M. Remili, D. Beldjerd, Stability and ultimate boundedness of solutions of some third order differential equations with delay. Journal of the Association of Arab Universities for Basic and Applied Sciences (2017)23, 90-95.
[14] M. Remili, D. Beldjerd, On ultimate boundedness and existence of periodic solutions of kind of third order delay differential equations. Acta Universitatis Matthiae Belii, series Mathematics Issue 2016, 1-15.
[15] M. Remili, D. Beldjerd, A boundedness and stability results for a kind of third order delay differential equations. Applications and Applied Mathematics, vol. 10, Issue 2 (Decembre 2015), 772-782.
[16] M. Remili, L. D. Oudjedi., Stability of the solutions of nonlinear third order differential equations with multiple deviating arguments. Acta Univ. Sapientiae, Mathematica, 8, 1 (2016) 150-165.
[17] M. Remili, L. D. Oudjedi., Boundedness and stability in third order nonlinear differential equations with bounded delay. Analele University Oradea Fasc. Matematica, Tom XXIII (2016), Issue No. 1, 135-143.
[18] D. R. Smart, Fixed points theorems, Cambridge University Press, Cambridge, 1980.
[19] Y.-Z. Tian, Y.-L. Cai, Y.-L. Fu, T.-X. Li. Oscillation and asymptotic behavior of third-order neutral differential equations with distributed deviating arguments. Adv. Difference Equ., 2015 (2015), 14 pages.
[20] C. Tunç, On the stability and boundedness of solutions to third order nonlinear differential equations with retarded argument. Nonlinear Dynam. 57 (2009), no. 1-2, 97-106. EJQTDE, 2010 No. 12, p. 18.
[21] C. Tunç, Some stability and boundedness conditions for non-autonomous differential equations with deviating arguments, E. J. Qualitative Theory of Diff. Equ., No. 1. (2010), pp. 1-12.
[22] C. Tunç, Existence of periodic solutions to nonlinear differential equations of third order with multiple deviating arguments. Int. J. Differ. Equ. 2012, Article ID 406835, 13 pp.
[23] C. Tunç, On the existence of periodic solutions of functional differential equations of the third order8. Appl. Comput. Math. 15 (2016), no. 2, 189-199.
[24] C. Tunç, Erdur, S., On the existence of periodic solutions to certain non-linear differential equations of third order. Proceedings of the Pakistan Academy of Sciences: A. Physical and Computational Sciences 54 (2): 207-218 (2017).
[25] T.-X. Li, C.-H. Zhang, G.-J. Xing, Oscillation of third-order neutral delay differential equations. Abstr. Appl. Anal., 2012 (2012), 11 pages.
[26] Yu, J. S. et al, Oscillation of neutral delay differential equation. Bull. Austral. Math. Soc. 45 (1992), 195-200.

## Author information

Anes MOULAI-KHATIR, Department of Mathematics. University Oran 1 Ahmed Ben Bella. 31000 Oran, Algeria. E-mail: anes.mkh@gmail.com

Moussadek REMILI, Department of Mathematics. University Oran 1 Ahmed Ben Bella. 31000 Oran, Algeria.
E-mail: remilimous@gmail.com
Djamila BELDJERD, Oran's High School of Electrical Engineering and Energetics. 31000 Oran, Algeria.
E-mail: dj.beldjerd@gmail.com

Received: February 2, 2019.
Accepted: June 23, 2019.

